

## Daftar Pustaka

- ATMEL Corporation. 2010. *8-bit Microcontroller with 2K Bytes In-System Programmable Flash ATtiny 2313*. (Online). (<http://www.atmel.com/Images/doc2543.pdf>). Diakses pada tanggal 15 November 2012.
- Borenstein, J. and Koren, Y., 1990, *Real-time obstacle avoidance for fast mobile robots in cluttered environments, ICRA '90*. International Conference on Robotics and Automation.
- Borenstein, J. and Koren, Y., 1990, *The Vector Field Histogram-Fast Obstacle Avoidance For Mobile robot*. International Conference on Robotics and Automation.
- Borenstein, J. and Koren, Y., 1991, *Potential Field Methods and Their Inherent Limitations for Mobile Robot Navigation*. International Conference on Robotics and Automation.
- Burnhill, Darren. 2009. *Ackerman Steering Principle*. (online). ([www.rctek.com](http://www.rctek.com)). Diakses pada tanggal 15 November 2012.
- Djati, Dmin. 2010. *Motor DC*. (Online). (<http://d-kecil.blogspot.com>). Diakses tanggal 16 November 2012.
- Eru Puspita, 2012 *Penentu Gerakan Mobile Robot Yang Belajar Sendiri Menggunakan Neural Network*. Jurnal Link Vol 16/No.1/Februari 2012.
- Lehrbaum, Rick. 2008. *Mobile-robot-packs-wireless-web-cam*. (Online). (<http://deviceguru.com>). Diakses pada tanggal 16 November 2012.
- R.L. Williams II, B. Carter, P. Gallina, and G. Rosati, 2002, *Dynamic Model with Slip for Wheeled Omnidirectional Robots*. IEEE Transactions on Robotics and Automation, 18(3): 285-293.
- Loutfi, A. 2005. *Object recognition: A new application for smelling robots*. Elsevier Science.
- Marques, L. 2002. *Olfaction-based mobile robot navigation*. Elsevier Science.

Odenthal,D.Ackermann,J.1999. *Advantages Of Active Steering For Vehicle Dymanics*. Control International Conference on Robotics and Automation.

Sutantra, Nyoman I, (2001). *Teknologi Otomotif Teori dan Aplikasinya*, Edisi Pertama, Penerbit Guna Widya, Surabaya, Surabaya.

