

DAFTAR PUSTAKA

- Atmel Corporation. (2011). *ATmega128*. San Jose, CA 95131.
- ELECTRONICS, R. 2010. *CMPS10 Tilt Compensated Magnetic Compass*. (online). (<http://www.innovativeelectronics.com/>)
- Hakim, L. (2009). *Implementasi perhitungan posisi robot dengan FPGA menggunakan rotary encoder*.(online).(<http://digilib.its.ac.id/public/ITS-paper-23036-2210105037-Paper.pdf>)
- Hanwei Electronics. (2007). *Technical Data MQ7 Gas Sensor*.
- Hartanti, E. D. 2011. *Rancang Bangun Mobile Robot Penjejak Benda Bergerak Berbasis Pengendali PD (Propositional-Derivative) Menggunakan Mikrokontroler AVR Atmega8535*. (online).(http://www.elektro.undip.ac.id/el_kpta/wp-content/uploads/2012/05/L2F003496_MTA.pdf).
- Hasanuddin, Z. A. 2007. *Konsep Dasar Pemetaan*. (online). (<http://geodesy.gd.itb.ac.id/hzabidin/wp-content/uploads/2007/05/konsep-dasar-pemetaan.pdf>).
- Lilienthal, A., & Duckett, T. 2004. *Building Gas Concentration gridmaps with a mobile robot*.
- MaxStream Inc. 2005. *XBee Pro OEM RF Module*. (online). (<http://www.libelium.com/squidbee/upload/3/31/Data-sheet-max-stream.pdf>).
- Prayogo, R. (2012). *Pengaturan PWM (Pulse Width Modulation dengan PLC)*. Malang.
- Rizqiawan, A. (2009, juni 12). *Rotary Encoder*. Diambil kembali dari Konversi ITB: <http://konversi.wordpress.com/2009/06/12/sekilas-rotary-encoder/>
- Singgeta, R. L. (2013). *Rancang Bangun Robot Boat Navigasi Tanpa Awak*. *e-jurnal Teknik dan Komputer*.
- ST. (2008, January 1). *Dual Full-Bridge Driver*.
- Utomo, A. D. (2007). *Sistem Kontrol Navigasi Pada Mobile Robot Berbasis PCBC (piecewise cubic bezier curve)*.

Vishay. (2004, 12 23). 16x2 Character LCD.

